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 Plan
 

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- 1 Diagonalisering av matriser
  - 2 Ortogonal diagonalisering
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Repetisjon:
 $A$   
 $n \times n$ 

Defn:  $\lambda$  eigenverdi for  $A$  hvis  $A\underline{v} = \lambda\underline{v} \Leftrightarrow (A - \lambda I)\underline{v} = \underline{0}$   
 har ikke-trivielle løsn ( $\underline{v} \neq \underline{0}$ )

$\lambda$  eigenverdi  $\Leftrightarrow |A - \lambda I| = 0$   
 kar. linn.

$E_\lambda = \{ \underline{v} : A\underline{v} = \lambda\underline{v} \}$  for en eigenverdi  $\lambda$   
eigenrommet til  $A$  med eigenverdi  $\lambda$

$\underline{v}$  eigenvektor  $\Leftrightarrow \underline{v} \in E_\lambda$  med  $\underline{v} \neq \underline{0}$   
 for  $A$  med  
 eigenverdi  $\lambda$

Defn.  $A$  er diagonaliserbar hvis det fins en  
 diagonal matrise  $D$  og en invertibel  
 matrise  $P$  slik at

$$P^{-1}AP = D$$

Metode: Finn eigenverdier og eigenvektorer  
 for  $A$ :  $A\underline{v}_i = \lambda_i \underline{v}_i$

$$P = \left( \underline{v}_1 \mid \underline{v}_2 \mid \dots \mid \underline{v}_n \right) \Rightarrow P^{-1}AP = D = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \end{pmatrix}$$

$P$  invertibel  $\Leftrightarrow$   
 $\{ \underline{v}_1, \underline{v}_2, \dots, \underline{v}_n \}$  lin. uabh.

$A$  diagonaliserbar  
 $\Uparrow$   
 $A$  har  $n$  lineært  
 uavhengige eigenvektorer

Ekso:  $A = \begin{pmatrix} 6 & 3 \\ -4 & -1 \end{pmatrix}$

Eigenverdier:  $|A - \lambda I| = 0$

$$\begin{vmatrix} 6-\lambda & 3 \\ -4 & -1-\lambda \end{vmatrix} = 0$$

$$\lambda^2 - \text{tr}(A) \cdot \lambda + \det(A) = 0$$

$$(6-\lambda)(-1-\lambda) - 3(-4) = 0$$

$$\lambda^2 - 5\lambda + 6 = 0$$

$$\lambda_1 = 2, \lambda_2 = 3$$

Eigenvektorer:

$\lambda = 2: E_2$

$A - \lambda I \rightarrow \begin{pmatrix} 4 & 3 \\ -4 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$4x + 3y = 0$ ,  $y$  fri  $x = -3y/4$

$\underline{v} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -3y/4 \\ y \end{pmatrix} = y/4 \begin{pmatrix} -3 \\ 4 \end{pmatrix}$

Basis for  $E_2$ :  $\underline{v}_1 = \begin{pmatrix} -3 \\ 4 \end{pmatrix}$

$\lambda = 3: E_3$

$\begin{pmatrix} 3 & 3 \\ -4 & -4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$3x + 3y = 0$ ,  $y$  fri  $x = -y$

$\underline{v} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ y \end{pmatrix} = y \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

Basis for  $E_3$ :  $\underline{v}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

To ~~kan~~ lineært uavhengige  
eigenvektorer:  $\underline{v}_1, \underline{v}_2$

$$\begin{vmatrix} -3 & -1 \\ 4 & 1 \end{vmatrix} = -3 + 4 = 1 \neq 0$$

I praksis gjør vi følgende:

i) Finner en basis for hvert enkelt egenrom.

ii) Slår sammen basisvektorene fra de ulike egenromene

$\Rightarrow$  lineært uavhengige eigenvektorer, og en minimal slik mengde

Merk: Eigenvektorer fra ulike egenrom er alltid lineært uavhengige.

Fordi:

$A \underline{v}_1 = \lambda_1 \underline{v}_1$  &  $\lambda_1 \neq \lambda_2$

$A \underline{v}_2 = \lambda_2 \underline{v}_2$

$x_1 \cdot \underline{v}_1 + x_2 \cdot \underline{v}_2 = \underline{0}$  | A.

$A x_1 \underline{v}_1 + A x_2 \underline{v}_2 = A \cdot \underline{0}$

$x_1 \cdot (\lambda_1 \underline{v}_1) + x_2 (\lambda_2 \underline{v}_2) = \underline{0}$

$x_1 \cdot \lambda_1 \underline{v}_1 + x_2 \lambda_1 \underline{v}_2 = \underline{0}$

trekker fra  $x_2 (\lambda_2 - \lambda_1) \underline{v}_2 = \underline{0}$

$\Rightarrow x_2 = 0 \Rightarrow x_1 = 0$

$\Rightarrow$  Lin. uavhengige vektorer

1. eks:  $P = \begin{pmatrix} -3 & -1 \\ 4 & 1 \end{pmatrix}$  og  $P^{-1}AP = D = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$

$\begin{matrix} \uparrow & \uparrow \\ \underline{v_1} & \underline{v_2} \end{matrix}$ 
 $\begin{matrix} \uparrow & \uparrow \\ \lambda_1 & \lambda_2 \end{matrix}$

Diagonaliserings av A.

Eks:

$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$\lambda^2 - 0\lambda + 1 = 0$$

$$\lambda^2 = -1$$

ingen egenverdier

A ikke diagonaliserbar

"for få egenverdier"

Eks:

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

$$\lambda^2 - 2\lambda + 1 = 0$$

$$(\lambda - 1)^2 = 0$$

$$\lambda_1 = \lambda_2 = 1$$

$$\lambda = 1: E_1$$

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$y = 0, x \text{ fri}$$

$$\underline{v} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ 0 \end{pmatrix} = x \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\underline{\text{Basis for } E_1: v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}}$$

$$P = \begin{pmatrix} 1 & ? \\ 0 & ? \end{pmatrix} \quad D = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

A ikke diagonaliserbar

"for få egenvektorer"

Resultat: A n×n-matrise

i) A er diagonaliserbar

$\Leftrightarrow$  A har n lineært uavhengige egenvektorer

ii) A har n forskjellige egenverdier  $\Rightarrow$  A diag. bar.

iii) A symmetrisk  $\Rightarrow$  A diag. bar



## ② Ortogonal diagonalisering

$A$   
 $n \times n$

Defn:  $A$  kalles ortogonal diagonaliserbar hvis det finnes en ortogonal matrise  $P$  slik at

$$P^{-1}AP = D \text{ er diagonal}$$

$$P^TAP$$

Minner om:

$$P = (v_1 | v_2 | \dots | v_n)$$

$$P^{-1} = P^T$$



$v_1, v_2, \dots, v_n$  er en ortonormal mengde

$$\begin{cases} v_i \cdot v_j = 0 & i \neq j \\ v_i \cdot v_i = 1 \end{cases}$$

I så fall kalles  $P$  en ortogonal matrise.

Resultat:

$$\begin{array}{c} A \text{ ortogonal diagonaliserbar} \\ \Updownarrow \\ A \text{ symmetrisk} \end{array}$$

Merk:  $A$  ortogonal diagonaliserbar  $\Leftrightarrow$  det finnes en ortonormal mengde av  $n$  egenvektorer for  $A$

Ex:  $A = \begin{pmatrix} 3 & 0 & 1 \\ 0 & 3 & 0 \\ 1 & 0 & 3 \end{pmatrix}$

Symmetrisk  $3 \times 3$

Egenverdier:

$$\begin{vmatrix} 3-\lambda & 0 & 1 \\ 0 & 3-\lambda & 0 \\ 1 & 0 & 3-\lambda \end{vmatrix} = 0 \quad + (3-\lambda) \cdot \begin{vmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{vmatrix} = 0$$

$$(3-\lambda) \cdot (\lambda^2 - 6\lambda + 8) = 0$$

$$(3-\lambda) \cdot (\lambda-2)(\lambda-4) = 0$$

$$\lambda_1 = 3 \quad \lambda_2 = 2 \quad \lambda_3 = 4$$

$$D = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix}$$

$$\underline{E_3:} \quad \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{matrix} x = 0 \\ y = 0 \\ z \text{ fri} \end{matrix} \quad \underline{v} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = y \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\underline{v_1} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\underline{E_2:} \quad \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{matrix} x+z=0 \\ y=0 \\ z \text{ fri} \end{matrix} \quad \underline{v} = \begin{pmatrix} -z \\ 0 \\ z \end{pmatrix} = z \cdot \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad \underline{v_2} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\underline{E_4:} \quad \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{matrix} -x+z=0 \\ -y=0 \\ z \text{ fri} \end{matrix} \quad \underline{v} = \begin{pmatrix} z \\ 0 \\ z \end{pmatrix} = z \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \quad \underline{v_3} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$a) \quad P = \begin{pmatrix} 0 & -1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} : \quad P^{-1}AP = D = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix} \quad \begin{matrix} \text{vanlig} \\ \text{diagonalisering} \end{matrix}$$

b) Er  $\underline{v_1}, \underline{v_2}, \underline{v_3}$  en ortogonal mengde?

$$\underline{v_1} \cdot \underline{v_2} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = 0 + 0 + 0 = 0$$

$$\underline{v_1} \cdot \underline{v_3} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = 0 + 0 + 0 = 0$$

$$\underline{v_2} \cdot \underline{v_3} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = -1 + 0 + 1 = 0$$

ortogonal mengde:  $\checkmark$

$$\underline{v_1} \cdot \underline{v_1} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = 1 \quad \|\underline{v_1}\| = \sqrt{1} = 1$$

$$\underline{v_2} \cdot \underline{v_2} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = 2 \quad \|\underline{v_2}\| = \sqrt{2} \neq 1$$

$$\underline{v_3} \cdot \underline{v_3} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = 2 \quad \|\underline{v_3}\| = \sqrt{2} \neq 1$$

ortonormal mengde: nei

Normalisering:  $\underline{w_1} = \frac{1}{\|\underline{v_1}\|} \cdot \underline{v_1} = (0, 1, 0)$

$$\underline{w_2} = \frac{1}{\|\underline{v_2}\|} \cdot \underline{v_2} = \frac{1}{\sqrt{2}} (-1, 0, 1)$$

$$\underline{w_3} = \frac{1}{\|\underline{v_3}\|} \cdot \underline{v_3} = \frac{1}{\sqrt{2}} (1, 0, 1)$$

Ortogonal diagonalisering

$$P = \begin{pmatrix} 0 & -1/\sqrt{2} & 1/\sqrt{2} \\ 1 & 0 & 0 \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$$

$$D = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix}$$

Merk:

Hvis  $A$  er symmetrisk, så er egenvektorer i forskjellige egenrom alltid ortogonale.