

# LECTURE 3

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DRE 7007

MATHEMATICS

PLAN:

- ① Functions and continuity .
- ② Derivatives and partial derivatives.

Reading:

- [FMEA] 13.3  
[MEJ] 13.4, 14  
[S] 1.4

# ① Functions and continuity

A function  $f: X \rightarrow Y$  is a rule that assigns a unique value  $y = f(x) \in Y$  to every element  $x \in X$ . The set  $X$  is called the domain and  $Y$  is called the codomain of  $f$ .

Most functions we consider are functions  $f: D \rightarrow \mathbb{R}$ , where the domain  $D \subseteq \mathbb{R}^n$  and the codomain is  $\mathbb{R}$ .

Example:  $f(x,y) = e^{xy} - 1$ , which can be written

$$g(x,y) = \frac{1}{x^2+y^2}, \quad (x,y) \neq (0,0)$$

can be written

$$\left\{ \begin{array}{l} f: \mathbb{R}^2 \rightarrow \mathbb{R} \\ (x,y) \mapsto e^{xy} - 1 \end{array} \right.$$

$$\text{with } D = \{(x,y) \in \mathbb{R}^2 : (x,y) \neq (0,0)\}$$

$$\left\{ \begin{array}{l} g: D \rightarrow \mathbb{R} \\ (x,y) \mapsto \frac{1}{x^2+y^2} \end{array} \right.$$

But also this is a function:

$$\left\{ \begin{array}{l} C([a,b], \mathbb{R}) \rightarrow \mathbb{R} \\ f \mapsto \int_0^1 f(x) dx \end{array} \right.$$

Such functions, where the domain consists of functions, are often called operators.

Let  $f: X \rightarrow Y$  be a function, where  $X$  and  $Y$  are metric spaces.

We say that  $f$  is continuous at  $x \in X$  if the following condition holds:

For any  $\varepsilon > 0$ , there is a  $\delta > 0$  such that

$$x' \in X \text{ with } d(x', x) < \delta \Rightarrow d(f(x'), f(x)) < \varepsilon$$

In other words,  $x' \in B(x, \delta) \Rightarrow f(x') \in B(f(x), \varepsilon)$

~~We say that  $f$  is continuous if it is continuous at  $x$  for all  $x \in X$ .~~

## Consequences of continuity:

### Theorem:

If  $f: X \rightarrow Y$  is continuous and  $K \subseteq X$  is compact, then

$$f(K) = \{y = f(x) : x \in K\} \subseteq Y$$

is also compact.

### Theorem: (Weierstrass) (Extreme value thm.)

If  $f: D \rightarrow \mathbb{R}$  is continuous, where  $D \subseteq \mathbb{R}^n$  is a closed and bounded set, then  $f$  has a maximum and a minimum.

### Proof:

$D$  is compact, so  $f(D)$  is compact. But the compact sets in  $\mathbb{R}$  are closed and bounded. Let  $M = \sup f(D)$  and  $m = \inf f(D)$ . Since  $f(D)$  is closed and bounded, there are  $x_{\max}$  and  $x_{\min}$  in  $D$  such that  $f(x_{\max}) = M$ ,  $f(x_{\min}) = m$ .

## How to determine if a function is continuous

- Facts:
- \* All "elementary" functions are continuous (polynomials, rationals, exponentials, logarithms).
  - \* Sums, products and quotients of continuous functions are cont.
  - \* Compositions of cont. functions are cont.

Ex:  $f(x) = \begin{cases} x+1, & x \geq 0 \\ e^x, & x < 0 \end{cases}$

$$f(x) = \begin{cases} 1, & x \text{ rational} \\ 0, & x \text{ irrational} \end{cases}$$

## Function spaces

Let  $D \subseteq X$  be a subset of a metric space  $X$ . Define

$$C(D) = \{f: D \rightarrow \mathbb{R} \mid f \text{ is continuous}\}$$

### Facts:

i)  $C(D)$  is a vector space

ii) The sup norm is a norm on  $C(D)$ , given by

$$\|f\|_{\sup} = \sup_{x \in D} |f(x)| = \sup \{ |f(x)| : x \in D \}$$

for  $f \in C(D)$ .

iii) If  $D$  is compact, then  $C(D)$  with sup norm is a complete metric space.

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### Note: Alternative defn. of continuity

$f: X \rightarrow Y$  cont. at  $x \in X$  if and only if the following condition holds,

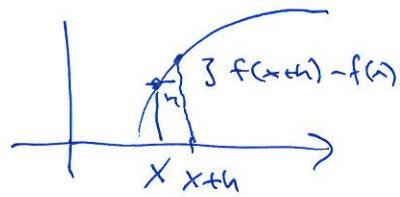
For any sequence  $(x_i)$  in  $X$  with  $\lim(x_i) = x$ , we have  $\lim(f(x_i)) = f(x)$ .

(2)

## Derivatives and partial derivatives

Recall: If  $f: \mathbb{R} \rightarrow \mathbb{R}$  is a function in one variable and  $x \in \mathbb{R}$ ,  
then

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$



Let  $f: D \rightarrow \mathbb{R}$ , where  $D \subseteq \mathbb{R}^n$  is an open set. For any  $\underline{x} \in D$ ,  
the partial derivatives

$$f'_i(\underline{x}) = \frac{\partial f}{\partial x_i}(\underline{x}) = \lim_{h \rightarrow 0} \frac{f(\underline{x} + e_i \cdot h) - f(\underline{x})}{h}$$

, where  $e_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix}$  (1 is in position i)

if this limit exists.

For any  $\underline{x} \in D$ , the total derivative is  $Df(\underline{x})$  if there is a  $1 \times n$ -matrix  
 $Df(\underline{x}) = A$  such that the following condition holds:

For any  $\varepsilon > 0$ , there is a  $\delta > 0$  such that

$$\forall \underline{y} \in D, \|\underline{y} - \underline{x}\| < \delta \Rightarrow \|f(\underline{y}) - f(\underline{x}) - A \cdot (\underline{y} - \underline{x})\| < \varepsilon \cdot \|\underline{y} - \underline{x}\|$$

In other words,

$$\lim_{\underline{y} \rightarrow \underline{x}} \frac{\|f(\underline{y}) - f(\underline{x}) - A(\underline{y} - \underline{x})\|}{\|\underline{y} - \underline{x}\|} = 0 \quad A = \left( \frac{\partial f}{\partial x_1}(\underline{x}) \quad \frac{\partial f}{\partial x_2}(\underline{x}) \quad \cdots \quad \frac{\partial f}{\partial x_n}(\underline{x}) \right)$$

If  $Df(\underline{x})$  exists, we say that  $f$  is differentiable in  $\underline{x}$ . If it is differentiable for all  $\underline{x} \in D$ ,  $f$  is called differentiable.

Facts:

- i) If  $f$  is differentiable at  $\underline{x} \in D$ , then all partial derivatives  $\frac{\partial f}{\partial x_i}(\underline{x})$  exists, and  $Df(\underline{x}) = \left( \frac{\partial f}{\partial x_1}(\underline{x}), \frac{\partial f}{\partial x_2}(\underline{x}), \dots, \frac{\partial f}{\partial x_n}(\underline{x}) \right)$ .
- ii) If all partial derivatives  $\frac{\partial f}{\partial x_i}(\underline{x})$  exists and are continuous at  $\underline{x}$ , then  $f$  is differentiable and  $Df(\underline{x}) = \left( \frac{\partial f}{\partial x_1}(\underline{x}), \dots, \frac{\partial f}{\partial x_n}(\underline{x}) \right)$ .

$f$  is called a  $C^1$  function if  $\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}$  exists and are continuous

### Facts:

- i) Sums of differentiable functions are differentiable
- ii) Composition of differentiable functions are differentiable.

Assume that  $f: D \rightarrow \mathbb{R}$  is a  $C^1$  function. We denote the  $j$ 'th partial derivative of  $(\partial f / \partial x_i): D \rightarrow \mathbb{R}$  by  $\frac{\partial^2 f}{\partial x_i \partial x_j} = f_{ij}''$  if it exists. We say that  $f$  is twice differentiable at  $x$ , with second derivative

$$D^2 f(x) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2}(x) & \frac{\partial^2 f}{\partial x_1 \partial x_2}(x) & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n}(x) \\ \vdots & \vdots & \ddots & \vdots \end{pmatrix}$$

in that case. The matrix  $D^2 f(x)$  is also called the Hessian of  $f$ .

We say that  $f$  is  $C^2$  if  $\frac{\partial^2 f}{\partial x_i \partial x_j}$  exists and is continuous for all  $i, j$ .

### Theorem:

If  $f: D \rightarrow \mathbb{R}$  is  $C^2$ , then the Hessian  $D^2 f(x)$  is a symmetric matrix.