

# DRE 70171

## Mathematics, Ph.D.

Department of Economics

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**Weight:** 100% of DRE 7017

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**Answer sheets:** Squares

**Examination support materials permitted:** BI-approved exam calculator. Simple calculator. Bilingual dictionary.

This exam consists of 10 problems of equal weight. **You must give reasons for your answers. Precision and clarity will be emphasized when evaluating your answers.**

**Question 1.**

Let  $I = [0, 1]$  be the unit interval, and consider the vector space  $V = C(I, \mathbb{R})$  of continuous functions on  $I$ , equipped with the inner product

$$f \cdot g = \int_0^1 f(t)g(t) dt$$

Compute  $f \cdot g$  when  $f(t) = t^a$  and  $g(t) = t^b$  for positive constants  $a, b > 0$ .

**Question 2.**

a) Find the stationary points of the following function, and classify them:

$$f(x, y, z) = x^2 + 2y^2 + 3z^2 + \sqrt{12}xz$$

b) Solve the following Kuhn–Tucker problem:

$$\max f(x, y) = x^2 - y^2 - x^3 \quad \text{when} \quad x^2 + y^2 \leq 1$$

**Question 3.**

A linear system of differential equations is given by

$$\dot{x} = 2x + z - 2$$

$$\dot{y} = -y - 5$$

$$\dot{z} = 2y + z - 4$$

a) Find the steady state  $(\bar{x}, \bar{y}, \bar{z})$  of the system.

b) Rewrite the system in the form  $\mathbf{w}' = A\mathbf{w}$ , determine all eigenvalues of  $A$ , and find three linearly independent eigenvectors for  $A$ .

c) Find the general solution to the linear system of differential equations, and show that

$$\lim_{t \rightarrow \infty} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \bar{x} \\ \bar{y} \\ \bar{z} \end{pmatrix}$$

when  $x(0) = -1$ ,  $y(0) = 10$ , and  $z(0) = -1$ .

**Question 4.**

Let  $f_1, \dots, f_m$  be real valued functions defined on a convex set  $S$  in  $\mathbb{R}^n$ . Show that if  $f_1, \dots, f_m$  are convex functions and  $a_1, \dots, a_m \geq 0$ , then the function

$$F = \sum_{i=1}^m a_i f_i$$

is convex.

**Question 5.**

Consider the following optimal control problem with control region  $U = [0, 1]$ :

$$\max_{u_t \in U} \sum_{t=0}^3 (5 - u_t)x_t^2 \quad \text{when} \quad \begin{cases} x_0 \text{ given} \\ x_{t+1} = u_t x_t \\ t = 0, 1, 2, 3 \end{cases}$$

Compute the value functions  $J_t(x)$  and the corresponding control functions  $u_t^*(x)$  for  $t = 0, 1, 2, 3$ , and solve the problem when  $x_0$  is given.

**Question 6.**

Let  $\mathbf{a} = (a_1, a_2) \neq (0, 0)$  and  $\mathbf{p} = (p_1, p_2)$  be given vectors in  $\mathbb{R}^2$ , and consider the following Lagrange problem:

$$\min f(x_1, x_2) = (p_1 - x_1)^2 + (p_2 - x_2)^2 \quad \text{when} \quad a_1 x_1 + a_2 x_2 = 0$$

- a) Find the minimum point  $\mathbf{x}^* = (x_1^*, x_2^*)$  of the Lagrange problem.
- b) Give a geometrical interpretation of  $\mathbf{x}^*$ , and show that  $\mathbf{x}^*$  and  $\mathbf{p} - \mathbf{x}^*$  are orthogonal vectors.