

Plan

- 1 Matrix multiplication and linear systems
- 2 Computing with matrices
- 3 Inverse matrices

Remember:

Midterm evaluation

New course paper:

14/03-21/03

① Matrix multiplication and linear systems

Defn: A, B matrices
and # cols in $A =$ # rows in B

$A \cdot B$ matrix multiplication of A by B

rows = # rows in A
cols = # cols in B

Ex:
$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 11 \\ 10 \end{pmatrix}$$

$1 \cdot 3 + 2 \cdot 4 = 11$
 $2 \cdot 3 + 1 \cdot 4 = 10$

$\underline{2 \times 2} = \underline{2 \times 1}$ 2×1

$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}^2 = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 5 & 4 \\ 4 & 5 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 5 & 4 \\ 4 & 5 \end{pmatrix}}}$$

$2 \times 2 \quad \text{---} \quad 2 \times 2$ 2×2

Note: $AB \neq BA$

Ex:
$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 11 \\ 10 \end{pmatrix}$$

$$\begin{pmatrix} 3 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \text{ not defined}$$

$2 \times 1 \neq 2 \times 2$

Formula for $A \cdot B$:

If $A \cdot B$ is defined, with
 $A = (a_{ij}), B = (b_{ij})$ then:

$AB = C = (c_{ij})$

with

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj}$$

Linear systems

Ex: $x + y + z + w = 4$
 $x - y + 2w = 7$
 $2x + 3y - z = 10$

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 0 & 2 \\ 2 & 3 & -1 & 0 \end{pmatrix}$$

coeff. matrix

$$\underline{b} = \begin{pmatrix} 4 \\ 7 \\ 10 \end{pmatrix}$$

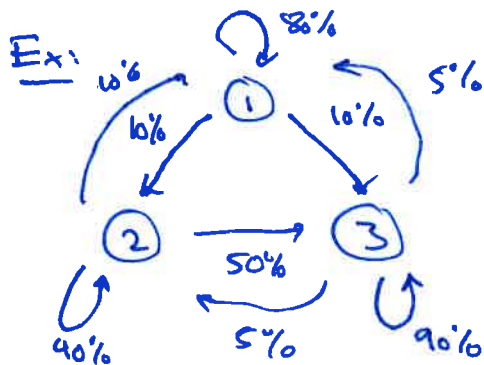
$$\underline{x} = \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$

$$A \cdot \underline{x} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 0 & 2 \\ 2 & 3 & -1 & 0 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} x + y + z + w \\ x - y + 2w \\ 2x + 3y - z \end{pmatrix} = \begin{pmatrix} 4 \\ 7 \\ 10 \end{pmatrix} = \underline{b}$$

That is; the linear system can be written

$$A \cdot \underline{x} = \underline{b}$$

(matrix form of the lin. sys.)



Starting state:

- 1 : 40%
- 2 : 30%
- 3 : 30%

$$A = \begin{pmatrix} 0.80 & 0.10 & 0.05 \\ 0.10 & 0.40 & 0.05 \\ 0.10 & 0.50 & 0.90 \end{pmatrix}$$

$$\underline{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

after one period

$$\rightarrow A \cdot \underline{v} = \begin{pmatrix} 0.80 & 0.10 & 0.05 \\ 0.10 & 0.40 & 0.05 \\ 0.10 & 0.50 & 0.90 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

$$= \begin{pmatrix} 0.80v_1 + 0.10v_2 + 0.05v_3 \\ 0.10v_1 + 0.40v_2 + 0.05v_3 \\ 0.10v_1 + 0.50v_2 + 0.90v_3 \end{pmatrix}$$

② Matrix algebra: Computing with matrices

Operations:

- 1) Addition, subtraction: $A+B, A-B$
- 2) Scalar multiplication: $C \cdot A$ (C : a number)
- 3) Matrix multiplication: $A \cdot B$
- 4) Powers: A^n defined when A is square and $n = 1, 2, 3, \dots$

Ex: $\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 5 & 4 \\ 4 & 5 \end{pmatrix}$

$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{pmatrix}$ not defined

$2 \times 3 \neq 2 \times 3$

$A^0 = I$

(identity matrix)

Special matrices: Identity matrix

$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \dots$

identity matrix
(of size $n \times n$)

Properties: $A \cdot I = A$ for any matrix A
 $I \cdot A = A$

Ex: $\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$

$\underbrace{\hspace{2em}}_A \cdot \underbrace{\hspace{2em}}_I = \underbrace{\hspace{2em}}_A$

$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$

$\underbrace{\hspace{2em}}_I \cdot \underbrace{\hspace{2em}}_A = \underbrace{\hspace{2em}}_A$

The transpose: $A \rightsquigarrow A^T$
 $n \times m$ matrix \rightsquigarrow $m \times n$ matrix transpose of A

Ex: $A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{pmatrix} \quad ; \quad A^T = \begin{pmatrix} 1 & 2 \\ 2 & 1 \\ 3 & 4 \end{pmatrix}$
 2×3 $\quad \quad \quad 3 \times 2$

$A = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 4 \\ 1 & 7 & 3 \end{pmatrix} \quad ; \quad A^T = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 7 \\ 0 & 4 & 3 \end{pmatrix}$
 3×3

Defn: A is a symmetric matrix if $A^T = A$.

Ex: $A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$, $B = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 4 \\ 0 & 4 & 7 \end{pmatrix}$ are symmetric
 $A^T = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$ $B^T = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 4 \\ 0 & 4 & 7 \end{pmatrix}$

Rules in matrix algebra

$$A + B = B + A$$

$$A \cdot (B + C) = AB + AC$$

$$A(BC) = (AB)C$$

⋮

$$AB \neq BA$$

$$(A+B)^2$$

$$= (A+B)(A+B)$$

$$= A^2 + BA + AB + B^2$$

$$\neq A^2 + 2AB + B^2$$

Determinant:

$$|A \cdot B| = |A| \cdot |B| \quad (\checkmark)$$

$$|c \cdot A| = c^n \cdot |A| \quad (A \text{ is } n \times n)$$

$$|A^T| = |A|$$

Transpose:

$$(A^T)^T = A$$

$$(AB)^T = B^T \cdot A^T \quad (\checkmark)$$

$$\left. \begin{matrix} x \neq 0 \\ \text{number} \end{matrix} \right\} x^{-1} = \frac{1}{x} \quad x \cdot x^{-1} = x \cdot \frac{1}{x} = 1$$

③ Inverse matrices

Defn: A $n \times n$ matrix. An inverse of A is a matrix A^{-1} such that

$$A \cdot A^{-1} = I \quad \text{and}$$

$$A^{-1} \cdot A = I$$

Ex: $A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$: $\begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \cdot \frac{1}{3} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

$|A| = 4 - 1 = 3 \neq 0$

The case $n=2$:

$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$:

- $|A| = ad - bc \neq 0$: $A^{-1} = \frac{1}{ad - bc} \cdot \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$
- $|A| = ad - bc = 0$: no inverse of A

- General facts:
- i) The inverse A does not always exist.
In fact, A is invertible (A^{-1} exists) if and only if $|A| \neq 0$.
 - ii) If A has an inverse, then it is unique.
 - iii) General formula for A^{-1} when $|A| \neq 0$:

$$A^{-1} = \frac{1}{|A|} \cdot \text{adj}(A) = \frac{1}{|A|} \cdot \begin{pmatrix} C_{11} & C_{12} & \dots & C_{1n} \\ C_{21} & C_{22} & \dots & C_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ C_{n1} & C_{n2} & \dots & C_{nn} \end{pmatrix}^T$$

Example:

$$\begin{matrix} 2x + y = 4 \\ x + 2y = 3 \end{matrix}$$

matrix form $\rightarrow \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \end{pmatrix}$ works if A^{-1} exists

$$\begin{aligned} A \cdot x &= b \quad | \cdot A^{-1} \\ A^{-1} \cdot A \cdot x &= A^{-1} \cdot b \\ I \cdot x &= A^{-1} \cdot b \\ x &= A^{-1} \cdot b \end{aligned}$$

$$\begin{aligned} x &= \frac{1}{3} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 3 \end{pmatrix} \\ \begin{pmatrix} x \\ y \end{pmatrix} &= \frac{1}{3} \begin{pmatrix} 5 \\ 2 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 5/3 \\ 2/3 \end{pmatrix}}} \end{aligned}$$

Ex:

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix}$$

$$|A| = \underline{+1 \cdot 6} - \underline{1 \cdot 5} + \underline{1 \cdot 1} = 2 \neq 0$$

$$A^{-1} = \frac{1}{2} \begin{pmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{pmatrix}^T = \frac{1}{2} \begin{pmatrix} 6 & -5 & 1 \\ -6 & 8 & -2 \\ 2 & -3 & 1 \end{pmatrix}^T$$

$$A^{-1} = \frac{1}{2} \begin{pmatrix} 6 & -6 & 2 \\ -5 & 8 & -3 \\ 1 & -2 & 1 \end{pmatrix}$$

$$c_{11} = +6$$

$$c_{12} = -5$$

$$c_{13} = +1$$

$$c_{21} = -6$$

$$c_{22} = +8$$

$$c_{23} = -2$$

$$c_{31} = +2$$

$$c_{32} = -3$$

$$c_{33} = +1$$