

Review of the spring curriculum

EBA1180
Spring
25

(a selection)

Part 1: Integration

Integration methods:

→ Substitution: New variable: $u(x)$

$$du = u' dx$$

$u'(x)$

$$dx = \frac{1}{u'} du$$

To recognize: Ugly inner function. Perhaps its derivative as a factor.

→ Integration by parts:

Prod. rule:

$$(u \cdot v)' = u'v + uv'$$

(use to derive int. by parts)

$$\int u' \cdot v dx = uv - \int u \cdot v' dx$$

To recognize: Product & something nice when anti-diff'ed.

→ Integration of rational functions:

i) $\int \frac{2}{1-x} dx$ ii) $\int \frac{2x}{1-x^2} dx$ iii) $\int \frac{2}{1-x^2} dx$

To solve: i) Substitute $u = 1-x$

ii) Substitute $u = 1-x^2$

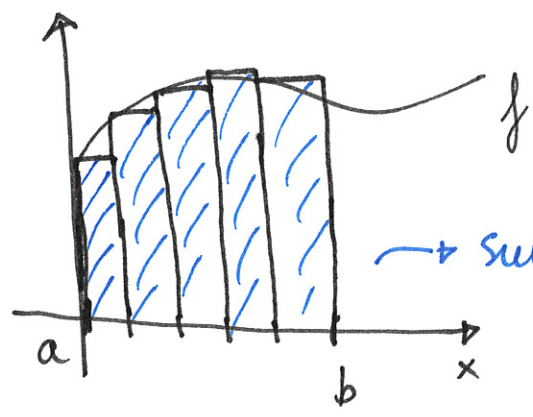
iii) Partial fractions: $\frac{2}{1-x^2} = \frac{A}{1+x} + \frac{B}{1-x}$. Solve for A and B and type (i) integral ①

Also works for: $\frac{ax+b}{cx^2+dx+e}$

Factor via abc-formula

Definite integrals: $\int_a^b f(x) dx = F(b) - F(a)$

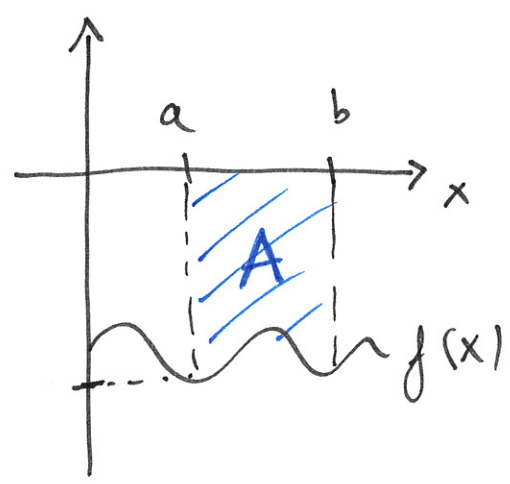
where $F'(x) = f(x)$.



→ sum of area of rectangles

area under graph of f between a and b = $\int_a^b f(x) dx$

width of rect. → 0



$A = - \int_a^b f(x) dx$

OBS!

Economic applications:

Tot. cash flow:

$\int_0^T f(x) dx$

cash flow per time unit

NPV of cash flow:
→ continuous discounting

$\int_0^T f(x) e^{-\Gamma x} dx$

discount rate

What's the plan?
Check your answers!

Part 2: Linear algebra

Thm: Any lin. syst. has either

- i) No solutions \rightarrow Inconsistent
 - ii) One unique solution
 - iii) Infinitely many solutions
- } \rightarrow Consistent

• $A+B$

• $A-B$

• rA

• $A \cdot B \Rightarrow$ # columns in $A =$ # rows in B NB:
 $A \cdot B \neq B \cdot A$

\rightarrow Determinants: For square matrices, $|A| = \det(A)$

2×2 : $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

$n \times n$: Cofactor expansion along row/column.

NB: Choose wisely! Lots of 0's make life easier.

Result: i) $|A| \neq 0 \Rightarrow$ One unique solution.

ii) $|A| = 0 \Rightarrow$ No solution or infinitely many solutions.

→ Linear combinations: $c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3$

→ Inverse matrices: Only for square matrices.

$$A^{-1} \text{ s.t. } A^{-1} A = I$$

$$A A^{-1} = I$$

Computing inverses:

$n \times n$: $|A| \neq 0$,

$$A^{-1} = \frac{1}{|A|}$$

$$\begin{bmatrix} c_{11} & c_{12} & \dots & c_{1n} \\ c_{21} & c_{22} & \dots & c_{2n} \\ \vdots & & \ddots & \vdots \\ c_{n1} & c_{n2} & \dots & c_{nn} \end{bmatrix}^T$$

where c_{ij} are cofactors.

Alt: $[A \mid I] \sim \dots \sim [I \mid A^{-1}]$

• $|A| = 0$: No inverse.

• If A^{-1} exists: $A \vec{x} = \vec{b}$

$$A^{-1} A \vec{x} = A^{-1} \vec{b}$$

$$I \vec{x} = A^{-1} \vec{b}$$

$$\underline{\underline{\vec{x} = A^{-1} \vec{b}}}$$

Part 3: Functions in two variables

Optimization without constraints

$$\max/\min f(x, y)$$

i) Find candidates for max/min:

I) Stationary points: $f'_x = 0$ and $f'_y = 0$

II) Points where f'_x or f'_y not def.

III) Boundary points.

ii) Classify candidates as loc. max/loc. min/
saddle pts:

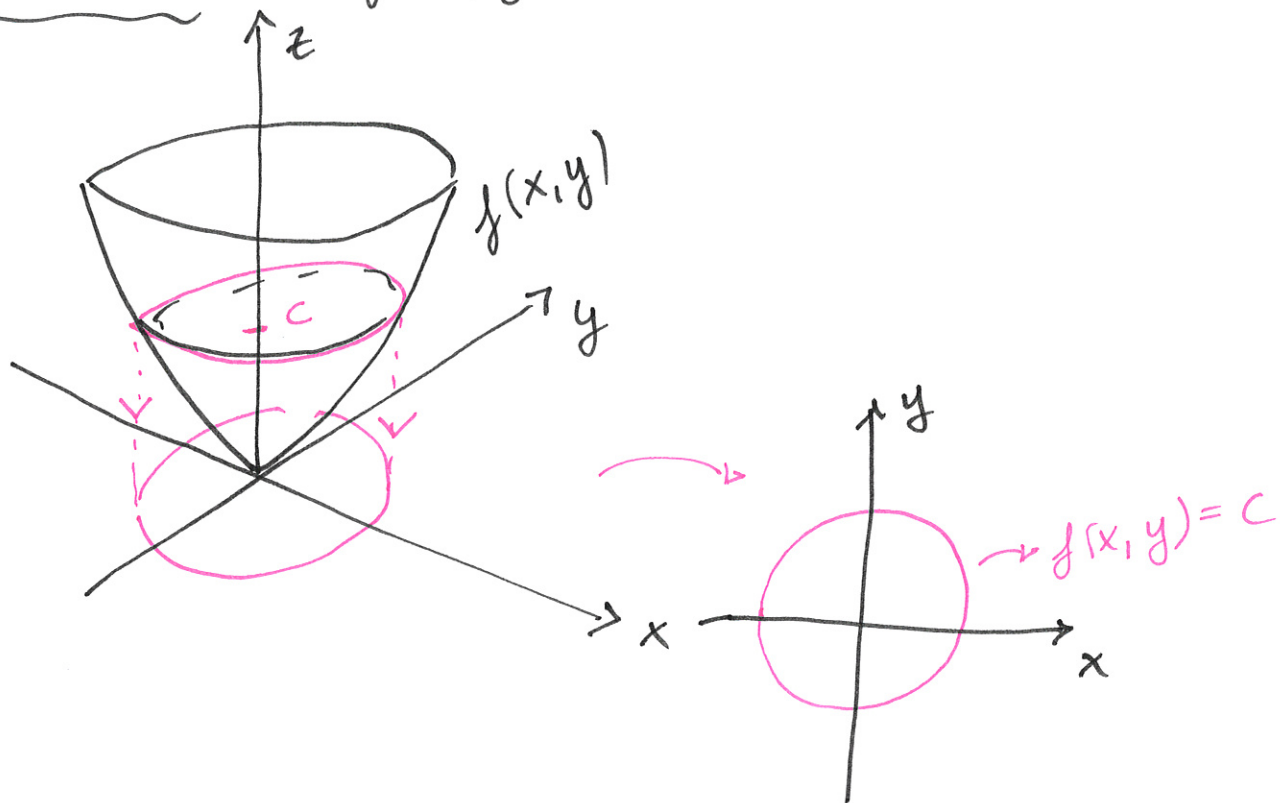
2nd derivative test

Not for boundary
or pts. where
partial deriv. not
def.

iii) Analyze whether loc. max./loc.
min. are global max/min.

Can ~~you~~ you find
smaller/bigger value
than local min/max
→ Not global min/max

Level curves: $f(x, y) = c$



Optimization with constraints

max/min $f(x, y)$ when ...

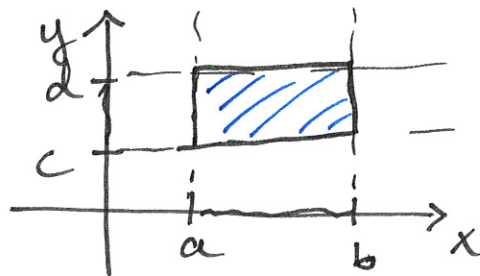
→ Constraints:
Equations,
inequalities

D = set of admissible points

Extreme value theorem (EVT): f is continuous and D is compact (closed and bounded), then f has a max. and a min. on D .

CASES

I) Optimization on a rectangle: $a \leq x \leq b$
 $c \leq y \leq d$



II) Lagrange problems:

$$\max/\min f(x,y) \text{ when } g(x,y)=a$$

Candidates for max/min:

i) Lagrange multiplier method:

$$L(x,y;\lambda) = f(x,y) - \lambda (g(x,y) - a)$$

Lagrange conditions:

$$L'_x = 0$$

$$L'_y = 0$$

$$\Rightarrow (x,y;\lambda):$$

$$c \{ g(x,y) = a$$

Ordinary
candidate
points.

ii) Admissible points with degenerate constraints:

$$g'_x = 0$$

$$g'_y = 0$$

$$g(x,y) = a$$

$$\Rightarrow (x,y) \text{ candidate}$$

III) Kuhn-Tucker problems: $\max/\min f(x,y)$ when

Candidates:

$$g(x,y) \leq a$$

i) Boundary: = \Rightarrow Lagrange problem.

ii) Interior stationary pts.

iii) Interior pts. where partial derivatives not def.

(e.g. cusps)