

LECTURE 3

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FORK 1003
MATHEMATICS

Plan:

- ① Determinants
- ② Inverse matrices and determinants.
- ③ Cramer's rule and linear systems

Review:

Matrices and vectors.

Addition / subtraction, scalar multiplication

Matrix multiplication - Identity matrix I .

$$A+B, A-B, rA \\ (\underline{v} + \underline{w}, \underline{v} - \underline{w}, r\underline{u})$$

Inverse matrices: Inverse of A is a matrix A^{-1} such that

$$\boxed{\begin{matrix} A^{-1}A = I \\ A \cdot A^{-1} = I \end{matrix}} \leftarrow \text{defn.}$$

Method: $(A|I)$

Gauss-Jordan elimination

Reduced echelon form

$$= (I | A^{-1}) \leftarrow A^{-1} \text{ exists and is}$$

$$(\neq I | *) \\ A^{-1} \text{ does not exist}$$

Linear system:

Matrix form:

$$A \cdot \underline{x} = \underline{b}$$

assume A^{-1} exists

$$A^{-1}(A\underline{x}) = A^{-1}\underline{b}$$

$$\boxed{\underline{x} = A^{-1}\underline{b}}$$

one unique solution

Matrix algebra rules:

$$A + B = B + A$$

$$A \cdot (B + C) = A \cdot B + A \cdot C$$

$$A \cdot (BC) = (AB) \cdot C$$

⋮

most rules are
the same as for
numbers

But:

$$A \cdot B \neq B \cdot A$$

no division for matrices

← Must instead multiply
with the inverse matrix
(if it exists; must choose
left or right mult.)

Transpose of a matrix A : A^T , A^t , A^*

Ex:

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

2×3

$$A^T = \begin{pmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{pmatrix}$$

3×2

$$A = \begin{pmatrix} \textcircled{1} & 2 \\ 3 & \textcircled{4} \end{pmatrix}$$

$$A^T = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$$

Defn: A is called symmetric if $A^T = A$

$$A = \begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix}$$

$$A^T = \begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix} = A$$

Rules for transposes:

$$(A + B)^T = A^T + B^T$$

$$(A - B)^T = A^T - B^T$$

$$(r \cdot A)^T = r \cdot A^T$$

$$(A \cdot B)^T = B^T \cdot A^T$$

① Determinants

A $n \times n$ -matrix (square) $\rightsquigarrow$ $\det(A) = |A|$
determinant of A
(a number)

$n=2$ case:

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} : |A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = \underline{ad - bc}$$

Ex: $\begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = 1 \cdot 4 - 2 \cdot 3 = 4 - 6 = \underline{\underline{-2}}$

Application: Inverse matrices

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} : \begin{cases} A^{-1} = \frac{1}{ad-bc} \cdot \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}, \overset{|A|}{ad-bc \neq 0} \\ A^{-1} \text{ does not exist if } \overset{|A|}{ad-bc = 0} \end{cases}$$

This means:

$$A^{-1} \text{ exists} \iff |A| \neq 0$$

(A invertible)

Also: $A\underline{x} = \underline{b}$
linear system
(A $n \times n$ -matrix)

$|A| \neq 0$: the linear system
has one solution

$|A| = 0$: the linear system
has either
no solutions
or
inf. many solutions

Case $n > 2$: Defn: Formula with $n!$ terms of degree n

$n=3$: $A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$

$$|A| = \underline{a}ei + \underline{b}fg + \underline{c}dh - \underline{c}eg - fh\underline{a} - i\underline{b}d$$

$n!$ terms of degree n

$$= a(ei - fh) + b(fg - id) + c(dh - eg)$$

Methods:

$$= a(ei - fh) - b(id - fg) + c(dh - eg)$$

(a) Cofactor expansion along a row or a column

Ex: $A = \begin{pmatrix} 1 & 2 & 4 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix} \quad \begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}$

$$|A| = +1 \cdot \begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 4 \\ 1 & 9 \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix}$$

$\uparrow$ $\uparrow$ $\uparrow$
 sign number from matrix minor

$$= 1 \cdot 6 + 1 \cdot (-5) + 1 \cdot 1$$

$$= 6 - 5 + 1 = \underline{\underline{2}}$$

$$= \underline{a_{11} \cdot C_{11} + a_{12} \cdot C_{12} + a_{13} \cdot C_{13}}$$

cofactors:

$$C_{11} = + \begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} = + (2 \cdot 9 - 3 \cdot 4) = \underline{6}$$

$$C_{12} = - \begin{vmatrix} 1 & 4 \\ 1 & 9 \end{vmatrix} = - (1 \cdot 9 - 1 \cdot 4) = \underline{-5}$$

$$C_{13} = + \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix} = + (1 \cdot 3 - 1 \cdot 2) = \underline{1}$$

$$\begin{pmatrix} + & - & + \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix}$$

$$\begin{aligned}
 & a_{11} \cdot C_{11} + a_{12} \cdot C_{12} + a_{13} \cdot C_{13} \\
 & \begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{vmatrix} = 1 \cdot \left(+ \begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} \right) + 1 \cdot \left(- \begin{vmatrix} 1 & 4 \\ 1 & 9 \end{vmatrix} \right) + 1 \cdot \left(+ \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix} \right) \\
 & = +1 \cdot \begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 4 \\ 1 & 9 \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix} \\
 & = 1 \cdot 6 \underbrace{(-1)}_{C_{12}} \cdot 5 + 1 \cdot 1 = 6 - 5 + 1 = \underline{\underline{2}}
 \end{aligned}$$

Fact: Cofactor expansion along any row or column will give the same result, $|A|$.

Ex: Cofactor expansion along second col. $|A| = a_{12} \cdot C_{12} + a_{22} \cdot C_{22} + a_{32} \cdot C_{32}$

$$\begin{aligned}
 & \begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{vmatrix} = 1 \cdot \left(- \begin{vmatrix} 1 & 4 \\ 1 & 9 \end{vmatrix} \right) + 2 \cdot \left(+ \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} \right) + 3 \cdot \left(- \begin{vmatrix} 1 & 1 \\ 1 & 4 \end{vmatrix} \right) \\
 & = -1 \cdot (9 - 4) + 2(9 - 1) - 3(4 - 1) = -5 + 16 - 9 = \underline{\underline{2}}
 \end{aligned}$$

Cofactor expansion works for any n .

$$|A| = a_{11} \cdot C_{11} + a_{12} \cdot C_{12} + a_{13} \cdot C_{13} + \dots + a_{1n} \cdot C_{1n}$$

(along first row in $n \times n$ -case)

Cofactors in general:

$$C_{ij} = \underbrace{(-1)^{i+j}}_{\text{sign}} \cdot M_{ij}$$

(row i ,
col. j)

$$\begin{pmatrix} + & - & + & - & + & - & \dots \\ - & + & - & + & - & + & \dots \\ + & - & + & - & + & - & \dots \\ - & + & - & + & - & + & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

minor in position (i,j)
= determinant of the submatrix you obtain by deleting row i and col. j .

Ex:

$$\begin{vmatrix} 0 & 7 & 3 & 4 \\ 1 & 0 & -1 & 2 \\ 2 & 1 & 0 & 1 \\ 0 & 4 & -1 & 2 \end{vmatrix} = 0 \cdot C_{11} + 1 \cdot C_{21} + 2 \cdot C_{31} + 0 \cdot C_{41}$$

$$= 1 \cdot \left(- \begin{vmatrix} 7 & 3 & 4 \\ 0 & -1 & 2 \\ 4 & -1 & 2 \end{vmatrix} \right) + 2 \cdot \left(+ \begin{vmatrix} 7 & 3 & 4 \\ 1 & 0 & 1 \\ 0 & -1 & 2 \end{vmatrix} \right)$$

$$= -1 \cdot \left(1 \cdot \left(- \begin{vmatrix} 3 & 4 \\ -1 & 2 \end{vmatrix} \right) + 1 \cdot \left(- \begin{vmatrix} 7 & 3 \\ 4 & -1 \end{vmatrix} \right) \right) \\ + 2 \cdot \left((-1) \cdot \left(+ \begin{vmatrix} 7 & 4 \\ 1 & 2 \end{vmatrix} \right) + 2 \cdot \left(- \begin{vmatrix} 7 & 3 \\ 1 & 0 \end{vmatrix} \right) \right)$$

$$= -1 \left(-10 - (-19) \right) + 2 \left(-(-2) - 2(-19) \right) \\ = -9 + 80 = \underline{\underline{71}}$$

Alternative method:

Ex:

$$\begin{vmatrix} 1 & 2 & 4 & 1 & 1 \\ 1 & 2 & 4 & 1 & 2 \\ 1 & 3 & 2 & 1 & 3 \end{vmatrix}$$

$$= 18 + 4 + 3 - 2 - 12 - 9 \\ = 25 - 23 = \underline{\underline{2}}$$



works only for $n=3$

Determinants using Gaussian elimination;

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix} \xrightarrow{\substack{R_2 - R_1 \\ R_3 - R_1}} B = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 2 & 8 \end{pmatrix}$$

$$|A| = ? \quad |B| = \underline{\underline{2}}$$

$$|B| = +1 \cdot \begin{vmatrix} 1 & 3 \\ 2 & 8 \end{vmatrix} = 2$$

Fact:

If you do one elementary row operation $A \rightarrow B$, then we have:

- If you switch two rows, then $|B| = -|A|$
- If you multiply a row by $c \neq 0$, then $|B| = c \cdot |A|$
- If you add a multiple of one row to another row, then $|B| = |A|$

Ex:

$$|A| = |B| = \underline{\underline{71}}$$

$$|B| = (-1) \cdot (-1) \cdot |A|$$

$$A = \begin{pmatrix} 0 & 7 & 3 & 4 \\ 1 & 0 & -1 & 2 \\ 2 & 1 & 0 & 1 \\ 0 & 4 & -1 & 2 \end{pmatrix} \xrightarrow{\substack{R_1 \leftrightarrow R_2 \\ R_3 - 2R_2}} \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 7 & 3 & 4 \\ 2 & 1 & 0 & 1 \\ 0 & 4 & -1 & 2 \end{pmatrix} \xrightarrow{R_3 - 2R_1} \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 7 & 3 & 4 \\ 0 & 1 & 2 & -3 \\ 0 & 4 & -1 & 2 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 7 & 3 & 4 \\ 0 & 1 & 2 & -3 \\ 0 & 4 & -1 & 2 \end{pmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 2 & -3 \\ 0 & 7 & 3 & 4 \\ 0 & 4 & -1 & 2 \end{pmatrix} \xrightarrow{\substack{R_1 + R_2 \\ R_3 - 7R_2 \\ R_4 - 4R_2}} \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 2 & -3 \\ 0 & 0 & -11 & 25 \\ 0 & 0 & -9 & 14 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 2 & -3 \\ 0 & 0 & -11 & 25 \\ 0 & 0 & -9 & 14 \end{pmatrix} = B$$

$$|B| = 1 \cdot \begin{vmatrix} 1 & 2 & -3 \\ 0 & -11 & 25 \\ 0 & -9 & 14 \end{vmatrix}$$

$$= 1 \cdot 1 \cdot (-11 \cdot 14 + 9 \cdot 25) = 225 - 154 = 71 //$$

Fact: If A is an upper triangular matrix:

$$A = \begin{pmatrix} a_1 & * & * & \dots & * \\ 0 & a_2 & * & \dots & * \\ 0 & 0 & a_3 & \dots & * \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & a_n \end{pmatrix}$$

all entries
under the
main
diagonal
are zero

then $|A| = \underline{a_1 \cdot a_2 \cdot \dots \cdot a_n}$

$$\begin{vmatrix} a_1 & * & * & * \\ 0 & a_2 & * & * \\ 0 & 0 & a_3 & * \\ 0 & 0 & 0 & a_4 \end{vmatrix} = a_1 \begin{vmatrix} a_2 & * & * \\ 0 & a_3 & * \\ 0 & 0 & a_4 \end{vmatrix}$$

$$= a_1 \cdot \left(a_2 \cdot \begin{vmatrix} a_3 & * \\ 0 & a_4 \end{vmatrix} \right) = a_1 \cdot a_2 \cdot (a_3 a_4) \\ = \underline{a_1 \cdot a_2 \cdot a_3 \cdot a_4}$$

② Determinants and inverses:

A nxn-matrix:

$$|A| \neq 0 \iff A^{-1} \text{ exists} \\ (A \text{ is invertible})$$

Formula for A^{-1} :

If $|A| \neq 0$, then

$$A^{-1} = \frac{1}{|A|} \cdot \text{adj}(A)$$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix};$$

$$ad - bc \neq 0;$$

$$A^{-1} = \frac{1}{ad - bc} \cdot \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$\text{adj}(A) = \begin{pmatrix} C_{11} & C_{12} & C_{13} & \dots & C_{1n} \\ C_{21} & C_{22} & C_{23} & \dots & C_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ C_{n1} & C_{n2} & C_{n3} & \dots & C_{nn} \end{pmatrix}^T$$

Ex:

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix}$$

$$|A| = 1 \cdot 6 + 1 \cdot (-5) + 1 \cdot 1 = 2$$

$$C_{11} = 6 \quad C_{12} = -5 \quad C_{13} = 1$$

extra comp. of cofactors

$$\begin{cases} C_{21} = -6 & C_{22} = 8 & C_{23} = -2 \\ C_{31} = 2 & C_{32} = -3 & C_{33} = 1 \end{cases}$$

$$A^{-1} = \frac{1}{2} \cdot \underbrace{\begin{pmatrix} 6 & -5 & 1 \\ -6 & 8 & -2 \\ 2 & -3 & 1 \end{pmatrix}^T}_{\text{adj}(A)} = \frac{1}{2} \begin{pmatrix} 6 & -6 & 2 \\ -5 & 8 & -3 \\ 1 & -2 & 1 \end{pmatrix}$$

③ Cramer's rule

Linear system $A\underline{x} = \underline{b}$ such that $\left\{ \begin{array}{l} \text{i) } A \text{ is } n \times n \text{ (square)} \\ \text{ii) } |A| \neq 0 \end{array} \right.$

In this case, we know that there is one unique solution

$$\begin{aligned} A\underline{x} &= \underline{b} \\ A^{-1}A\underline{x} &= A^{-1}\underline{b} \\ \underline{x} &= A^{-1}\underline{b} \end{aligned}$$

Since $|A| \neq 0 \Rightarrow A^{-1}$ exists.

Cramer's rule: Formula for this solution (that is, another formula)

$$\underline{x}_1 = \frac{|A_1(\underline{b})|}{|A|}$$

← $A_1(\underline{b})$: replace col. 1 in A with $\underline{b}$

$$\underline{x}_2 = \frac{|A_2(\underline{b})|}{|A|}$$

← $A_2(\underline{b})$: replace col. 2 in A with $\underline{b}$

⋮

$$\underline{x}_n = \frac{|A_n(\underline{b})|}{|A|}$$

← $A_n(\underline{b})$: replace col. n in A with $\underline{b}$

Ex:

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 7 \\ 13 \end{pmatrix}$$

$|A| = 2 \neq 0 \Rightarrow$ one solution (x, y, z)

$$\left. \begin{aligned} |A_1(\underline{b})| &= \begin{vmatrix} 3 & 1 & 1 \\ 7 & 2 & 4 \\ 13 & 3 & 9 \end{vmatrix} = 3 \cdot 6 - 1 \cdot 11 + 1 \cdot (-5) \\ &= 18 - 11 - 5 = 2 \end{aligned} \right\} \Rightarrow x = \frac{|A_1(\underline{b})|}{|A|} = \frac{2}{2} \\ \underline{\underline{x = 1}} \end{aligned}$$

(similar for y and z)