

Plan:

- ① Extended Review: Lecture 3
- ② Eigenvalues and eigenvectors
- ③ Diagonalization

Reminder:

Plenary Session I on Mond. at 1700-2000 in A1-040

Problems: Selected from Lecture 1-4
(Key problems + Workbook problems)

① Review: Lecture 3

$$\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n\} \rightsquigarrow A = (\underline{v}_1 | \underline{v}_2 | \dots | \underline{v}_n)$$

m-vectors m x n-matrix

Key notions:

- linear combination of $\{\underline{v}_1, \dots, \underline{v}_n\}$
- $\text{span}(\underline{v}_1, \dots, \underline{v}_n)$
- linear independence of $\{\underline{v}_1, \dots, \underline{v}_n\}$

V vector space: $\begin{cases} \underline{v}, \underline{w} \text{ in } V \Rightarrow \\ \underline{v} + \underline{w} \text{ in } V, r\underline{v} \text{ in } V \end{cases}$

$V = \text{span}(\underline{v}_1, \dots, \underline{v}_n)$ vector space
 $\dim V = \text{rk}(A)$ ← # pivot Pos. in A

$\{\underline{v}_1, \dots, \underline{v}_n\}$ linearly independent

\Updownarrow

no vector is in the span of the others

\Updownarrow

$x_1\underline{v}_1 + \dots + x_n\underline{v}_n = \underline{0}$ has only the trivial solution $\leftrightarrow A \cdot \underline{x} = \underline{0}$ has only the zero (trivial) solution

\Updownarrow

$\text{rk}(A) = n$ ← no free variables

$V = \text{span}(v_1, \dots, v_n)$:

A subset $B \subseteq \{v_1, \dots, v_n\}$ is called a base for V if

- i) $\text{span}(B) = V$
- ii) B is linearly independent

You may choose B to be the vectors corresponding to pivot positions in A .



The number of vectors in B will be $\dim(V)$.

- Null(A): $\text{Null}(A) = \text{solutions of } Ax = \underline{0}$
 $W = \text{Null}(A)$ is a vector space

$\dim W = n - \text{rk}(A)$

$W = \text{span}(w_1, \dots, w_r)$

$r = \dim W$ if the vectors w_1, \dots, w_r are chosen minimally

Important fact:

$V = \text{span}(v_1, \dots, v_n)$
 $W = \text{Null}(A)$

$\dim V = \text{rk}(A)$
 $\dim W = n - \text{rk}(A)$

← # pivot pos. in A
 ← # col's without pivots in A

Ex: $A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 0 \\ 3 & 4 & 2 \end{pmatrix} \Rightarrow v_1 = \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} \quad v_2 = \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix} \quad v_3 = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$

$V = \text{span}(v_1, v_2, v_3)$
 $\dim V = 2$
 $B = \{v_1, v_2\}$ base of V

$\dim A = 1 \cdot (-2) + 2 \cdot 1 = 0$
 $\text{rk } A = 2$

$\{v_1, v_2\}$ lin. independent
 v_3 is in $\text{span}(v_1, v_2)$

$W = \text{Null}(A)$: Sol. of $Ax = \underline{0}$
 $\dim W = 1$ (one free var. x_2)
 $w_1 = \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix} \quad W = \text{span}(w_1)$

$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 2 & 0 & 0 \\ 3 & 4 & 2 & 0 \end{array} \right) \xrightarrow{-1} \left(\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & -1 & 0 \end{array} \right)$

$x_1 = -x_2 - x_3$
 $x_2 = x_3$

$-2v_1 + v_2 + v_3 = \underline{0}$
 $v_3 = 2v_1 - v_2$

$x = \begin{pmatrix} -2x_3 \\ x_3 \\ x_3 \end{pmatrix} = x_3 \cdot \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}$

② Eigenvectors and eigenvalues

Linear transformation

A
($n \times n$ -matrix)

Ex: $A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$

$$f(\underline{x}) = A \cdot \underline{x}$$

eigen-vector \rightarrow $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \end{pmatrix} = 4 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ eigen-value

$\begin{pmatrix} 2 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 7 \\ 5 \end{pmatrix} \neq \lambda \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

Defn: λ is called an eigenvalue of A if $A \cdot \underline{x} = \lambda \cdot \underline{x}$ has non-trivial solutions for \underline{x} . If λ is an eigenvalue of A ; then all solutions of $A \cdot \underline{x} = \lambda \underline{x}$ are called eigenvectors for A with eigenvalue λ .

Ex: $A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$: $\begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \lambda \cdot \begin{pmatrix} x \\ y \end{pmatrix}$

$$3x + y = 2x$$

$$x + 3y = 2y$$

$$(3x - 2x) + y = 0$$

$$x + (3y - 2y) = 0$$

$$\begin{pmatrix} 3-2 & 1 \\ 1 & 3-2 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

non-trivial solutions

$$\begin{vmatrix} 3-2 & 1 \\ 1 & 3-2 \end{vmatrix} = 0$$

$$(3-2)^2 - 1 = 0$$

$$9 - 6\lambda + \lambda^2 - 1 = 0$$

$$\lambda^2 - 6\lambda + 8 = 0$$

characteristic eqn.

$$\lambda_1 = 4, \lambda_2 = 2$$

← eigenvalues

In general:

$$A \cdot \underline{x} = \lambda \underline{x}$$

$$A \cdot \underline{x} - \lambda \underline{x} = \underline{0}$$

$$A \cdot \underline{x} - \lambda I \cdot \underline{x} = \underline{0}$$

$$(A - \lambda I) \underline{x} = \underline{0}$$

homogeneous linear system

Method for finding eigenvalues:

A
 $n \times n$

\longrightarrow Characteristic equation:

$$|A - \lambda I| = 0$$

$(A - \lambda I)\underline{x} = \underline{0}$
has non-trivial
solutions

Solutions for $\lambda =$ eigenvalues of A

Ex: $A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$:

$$\begin{vmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{vmatrix} = 0$$

$$(3-\lambda)^2 - 1 = 0$$

$$\lambda^2 - 6\lambda + 8 = 0$$

$$\lambda_1 = 4, \lambda_2 = 2$$

Ex: $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$:

$$\begin{vmatrix} a-\lambda & b \\ c & d-\lambda \end{vmatrix} = 0$$

$$(a-\lambda)(d-\lambda) - bc = 0$$

$$\lambda^2 - (a+d)\lambda + (ad-bc) = 0$$

$$\lambda^2 - \text{tr}(A) \cdot \lambda + \det(A) = 0$$

$\text{tr } A =$ sum of all
diagonal entries
 $= a_{11} + a_{22} + \dots + a_{nn}$

Formula for characteristic eqn.
for all 2×2 -matrices:

Method for finding eigenvectors

when the eigenvalues are known.

E₁: $A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$

Eigenvalues:

$\lambda_1 = 4, \lambda_2 = 2$

$\lambda = 4$: $A\underline{x} = \lambda\underline{x}$

$(A - \lambda I)\underline{x} = \underline{0} \rightarrow \lambda = 4$

$\begin{pmatrix} 3-4 & 1 \\ 1 & 3-4 \end{pmatrix}$

$\begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$-1x + 1y = 0$

$\begin{cases} x = y \\ y = \text{free} \end{cases}$

$\underline{x} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ y \end{pmatrix} = y \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

Space of all eigenvectors for $\lambda = 4$

$E_4 = \text{Null}(A - 4I)$

$= \text{span}(\underline{w}_1), \underline{w}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\lambda = 2$:

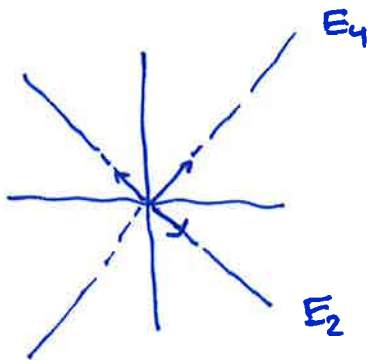
$\begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \end{pmatrix}$

$x + y = 0$
 y free

$\underline{x} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ y \end{pmatrix} = y \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

$E_2 = \text{span}(\underline{w}_2), \underline{w}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

$A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$



In general: $E_\lambda = \text{Null}(A - \lambda I)$
 = all eigenvectors for A
 with eigenvalue λ

$(A - \lambda I) \cdot \underline{x} = \underline{0}$ ← solve this homogeneous linear system

$\dim E_\lambda = \# \text{ free variables}$

Facts:

A
 $(n \times n)$

* The characteristic equation has the form

$$|A - \lambda I| = 0 \Leftrightarrow (-\lambda)^n + \dots = 0$$

↑
lower degree terms

It is a polynomial equation of degree n .

* If A is symmetric, then A has n eigenvalues $\lambda_1, \dots, \lambda_n$ (counted with multiplicities)

* If A has n eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ (counted with multiplicities), then

$$|A| = \lambda_1 \cdot \lambda_2 \cdot \dots \cdot \lambda_n$$

$$\text{tr}(A) = \lambda_1 + \lambda_2 + \dots + \lambda_n$$

* For an eigenvalue λ of multiplicity m , we have that

$$1 \leq \dim E_\lambda \leq m$$

↑
free var.

$$(A - \lambda I)\underline{x} = \underline{0}$$

If A is symmetric, then $\dim E_\lambda = m$ for all λ .

Ex: $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$: $\begin{vmatrix} 1-\lambda & 1 \\ -1 & -\lambda \end{vmatrix} = 0$
 $\lambda^2 + 1 = 0$
 $\lambda^2 = -1 \leftarrow$ no. eigenvalues

$A = \begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix}$: $\begin{vmatrix} 1-\lambda & 3 \\ 0 & 1-\lambda \end{vmatrix} = 0$
 $(1-\lambda)^2 = 0$
 $\lambda = 1$ has multiplicity ~~1~~ 2 $\rightarrow \underline{\lambda_1 = \lambda_2 = 1}$
 $\lambda^2 - 2\lambda + 1 = 0$
 $\lambda = \frac{2 \pm \sqrt{4 - 4 \cdot 1 \cdot 1}}{2}$
 $= \frac{2 \pm 0}{2}$
 $\lambda_1 = 1 \quad \lambda_2 = 1$

$A = \begin{pmatrix} 1 & 0 & 3 \\ 0 & -2 & 0 \\ 3 & 0 & 1 \end{pmatrix}$: $\begin{vmatrix} 1-\lambda & 0 & 3 \\ 0 & -2-\lambda & 0 \\ 3 & 0 & 1-\lambda \end{vmatrix} = 0$
 $(-2-\lambda) \cdot ((1-\lambda)^2 - 9) = 0$
 $(-2-\lambda) \cdot (\lambda^2 - 2\lambda - 8) = 0$
 $\underline{\lambda = -2}$ or $\lambda^2 - 2\lambda - 8 = 0$
 $\lambda = \frac{2 \pm \sqrt{4 - 4 \cdot (-8)}}{2}$
 $= \frac{2 \pm 6}{2}$
 $\underline{\lambda = -2}, \underline{\lambda = 4}$

$\lambda_1 = -2, \lambda_2 = -2, \lambda_3 = 4$
 mult. 2

③ Diagonalization

A
($n \times n$
matrix)

Defn: A is diagonalizable if there is a diagonal matrix D and an invertible matrix P such that

$$P^{-1}AP = D$$

Key result:

A is diagonalizable if and only if:

$$D = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{pmatrix} \rightarrow$$

i) A has n eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ (counted with multiplicity), and

ii) A has n linearly independent eigenvectors $\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n$ (with $A\underline{v}_i = \lambda_i \underline{v}_i$)

$$P = \begin{pmatrix} | & | & & | \\ \underline{v}_1 & \underline{v}_2 & \dots & \underline{v}_n \\ | & | & & | \end{pmatrix} \rightarrow$$

In particular:

A symmetric $\implies A$ diagonalizable

Why?

$$\begin{aligned} A \cdot P &= A \cdot (\underline{v}_1 | \underline{v}_2 | \dots | \underline{v}_n) = (A\underline{v}_1 | A\underline{v}_2 | \dots | A\underline{v}_n) \\ &= (\lambda_1 \underline{v}_1 | \lambda_2 \underline{v}_2 | \dots | \lambda_n \underline{v}_n) = (\underline{v}_1 | \underline{v}_2 | \dots | \underline{v}_n) \cdot \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{pmatrix} \\ &= P \cdot D \end{aligned}$$

$$AP = PD \implies \boxed{P^{-1}AP = D}$$

Ex: $A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$

$$\lambda_1 = 4, \lambda_2 = 2$$

$$E_4 = \text{span}(\underline{w}_1), \underline{w}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$E_2 = \text{span}(\underline{w}_2), \underline{w}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$D = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$P^{-1}AP = D$$

A diagonalizable

Result:

(assume that A has n eigenvalues $\lambda_1, \dots, \lambda_n$)

There are n linearly independent eigenvectors



For each eigenvalue (of multiplicity m), we have $\dim E_\lambda = m$.

Ex:

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

Eigenvalues:

$$\begin{vmatrix} 1-\lambda & 1 & 0 \\ 0 & 1-\lambda & 0 \\ 0 & 0 & 3-\lambda \end{vmatrix}$$

$$= (1-\lambda)(1-\lambda)(3-\lambda) = 0$$

$$\lambda_1 = 1, \lambda_2 = 1, \lambda_3 = 3$$

For any upper triangular matrix, the eigenvalues are the diagonal entries.

$$D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

A is not diagonalizable
not enough eigenvectors

$$\lambda = 3: \begin{pmatrix} -2 & 1 & 0 & | & 0 \\ 0 & -2 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$$x = \begin{pmatrix} 0 \\ 0 \\ z \end{pmatrix} = z \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad \begin{matrix} x=0 \\ y=0 \end{matrix}$$

$$E_3 = \text{span}(\underline{w}_3), \underline{w}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda = 1: \begin{pmatrix} 0 & 1 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \quad \begin{matrix} y=0 \\ z=0 \\ x \text{ free} \end{matrix}$$

$$x = \begin{pmatrix} x \\ 0 \\ 0 \end{pmatrix} = x \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$E_1 = \text{span}(\underline{w}_1), \underline{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Consequence:Result:

If A has n eigenvalues, all of multiplicity 1,
then A is diagonalizable.

Note: ① A symmetric \Rightarrow A diagonalizable

— but there are non-symmetric matrices that are diagonalizable as well

Ex: $A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ not symmetric
not diagonalizable (no eigenvalues)

$A = \begin{pmatrix} 1 & 2 \\ 0 & 3 \end{pmatrix}$ not symmetric
diagonalizable $\lambda_1 = 1, \lambda_2 = 3$
 $\underline{w}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \underline{w}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

② A has n eigenvalues of multiplicity 1 \Rightarrow A diagonalizable

— but there are matrices with eigenvalues of higher multiplicity that are diagonalizable

Ex: $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$ $\lambda = 1$ (mult 2)
 A is not diagonalizable

$A = \begin{pmatrix} 1 & 0 & 3 \\ 0 & -2 & 0 \\ 3 & 0 & 1 \end{pmatrix}$ $\lambda = -2$ (mult 2)
 A is diagonalizable (it is symmetric)