

Plan

- 1 Linear difference equations
- 2 Systems of linear first order difference equations
- 3 Equilibrium states and stability

← Note for eq. states / stability → not in the curriculum this year.

① Linear difference equations

Ex: $y_{t+1} = 1.04 y_t$, $y_0 = 100$

$\underbrace{\hspace{10em}}$ difference eqn. $\underbrace{\hspace{10em}}$ initial condition

$$y_1 = 1.04 y_0 = 104$$

$$y_2 = 1.04 \cdot y_1 = 1.04 (1.04 y_0) = 1.04^2 y_0 = 108.16$$

$$y_3 = 1.04 y_2 = 1.04 (1.04^2 y_0) = 1.04^3 y_0$$

⋮

$$y_t = 1.04^t \cdot y_0$$

$$= 100 \cdot 1.04^t$$

$$t = 0, 1, 2, \dots$$

general solution
particular solution

Note: - the solutions of a difference equation are sequences $(y_0, y_1, y_2, \dots, y_t, \dots)$

- we write y_t for sequences, as opposed to $y(t)$ for cont. functions - we only have values for $t = 0, 1, 2, \dots$

- we can rewrite $y_{t+1} = 1.04 y_t$ as $y_{t+1} - y_t = 0.04 y_t$

First order difference equation:

Egn. with y_{t+1} and y_t

$\underbrace{\hspace{10em}}$
difference in the seq.

Compare:

$$y' = 0.04 y$$

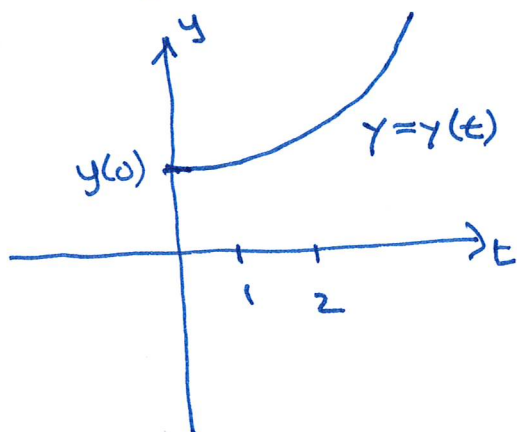
$$y' - 0.04 y = 0$$

$$y = C \cdot e^{0.04t}$$

$$e^{rt}$$

$$y(0) = C \cdot e^0 = C$$

$$y = y(0) e^{0.04t}$$



Differential equations
= change in cont. time

$$y_{t+1} - y_t = 0.04 y_t$$

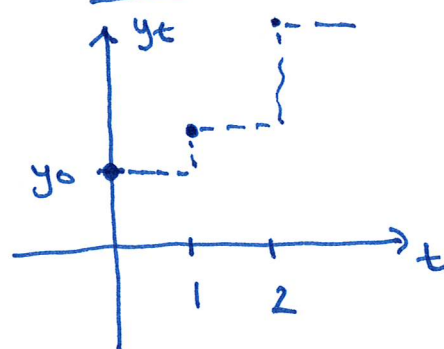
$$y_{t+1} = 1.04 y_t$$

$$y_{t+1} - 1.04 y_t = 0$$

$$y_t = C \cdot 1.04^t$$

$$y_0 = C \cdot 1 = C$$

$$y_t = y_0 \cdot 1.04^t$$



Difference equations
= change in discrete time

$r = \text{char. root}$
 $\downarrow$
 r^t
 or
 $(1+r)^t$
 $r = \text{interest}$

Linear first order difference equations with constant coefficients.

$$\boxed{Y_{t+1} + aY_t = b_t} \quad \text{where} \quad \begin{array}{l} a = \text{constant} \\ b_t = \text{sequence} \end{array}$$

Ex: $Y_{t+1} - 1.10Y_t = -300$ $\begin{cases} a = -1.10 \\ b = -300 \end{cases}$

Solution method: Superposition

$$Y_t = Y_t^h + Y_t^p = \underline{C \cdot 1.10^t + 3000}$$

Y_t^h : $Y_{t+1} - 1.10Y_t = 0$

Char. eqn: $r - 1.10 = 0$
 $\underline{r = 1.10} \quad Y_t^h = \underline{C \cdot 1.10^t}$

Y_t^p : $Y_{t+1} - 1.10Y_t = -300$ guess:

$Y_t = A$ (constant soln)
 $Y_{t+1} = A$

$$A - 1.10A = -300$$

$$\begin{array}{r} -0.10A = -300 \\ \hline -0.10 \quad -0.10 \end{array}$$

$$A = \underline{3000} \quad Y_t^p = \underline{3000}$$

Interpretation:

$$Y_{t+1} - 1.10Y_t = -300$$

$$Y_{t+1} - Y_t = 0.10Y_t - 300$$

$$Y_t = C \cdot 1.10^t + 3000$$

$$t=0: Y_0 = C \cdot 1 + 3000$$

$$C = Y_0 - 3000$$

bank acc.
with interest 10%
and 300 withdrawal
each term

$$\begin{aligned} Y_t &= (Y_0 - 3000) \cdot 1.10^t + 3000 \\ &= Y_0 \cdot 1.10^t - 3000(1.10^t - 1) \end{aligned}$$

Char. eqn: $Y_t = r^t$
 $Y_{t+1} = r^{t+1}$
 $= r^t \cdot r = r \cdot r^t$
 $r \cdot r^t - 1.10 \cdot r^t = 0$
 $r^t \cdot (r - 1.10) = 0$
 $\underline{r - 1.10 = 0}$

Second order linear difference equations with const. coeff.

$$Y_{t+2} + aY_{t+1} + bY_t = c_t \quad \text{when } \begin{cases} a, b & \text{constants} \\ c_t & \text{seq.} \end{cases}$$

Ex: $Y_{t+2} - 3Y_{t+1} + 2Y_t = 0$

Solution method: Superposition

$$Y_t = Y_t^h + Y_t^p = Y_t^h = \underline{\underline{C_1 + C_2 \cdot 2^t}}$$

Y_t^h : $Y_{t+2} - 3Y_{t+1} + 2Y_t = 0$

$$r^2 - 3r + 2 = 0$$

$$\underline{r=1}, \underline{r=2} \rightarrow Y_t^h = C_1 \cdot 1^t + C_2 \cdot 2^t = \underline{\underline{C_1 + C_2 \cdot 2^t}}$$

Ex: $Y_{t+2} - 4Y_{t+1} + 4Y_t = 0$

$$Y_t = \underline{\underline{(C_1 + C_2 t) \cdot 2^t}}$$

Y_t^h : $r^2 - 4r + 4 = 0$

$$(r-2)^2 = 0$$

$$r_1 = r_2 = \underline{\underline{2}}$$

$$\rightarrow Y_t^h = \underline{\underline{C_1 \cdot 2^t + C_2 t \cdot 2^t}}$$

Ex: $y_{t+2} - 3y_{t+1} + 2y_t = 4t$

$c_t = 4t$

$$y_t = y_t^h + y_t^p = \underline{\underline{c_1 \cdot 1^t + c_2 \cdot 2^t - 2t^2 - 2t}} = \underline{\underline{c_1 + c_2 \cdot 2^t - 2t^2 - 2t}}$$

$y_t^h: r^2 - 3r + 2 = 0$
 $r = 1, 2$

$y_t^h = \underline{\underline{c_1 \cdot 1^t + c_2 \cdot 2^t}}$

y_t^p : $y_{t+2} - 3y_{t+1} + 2y_t = \textcircled{4t}$

~~$y_t = A + B$~~

~~$y_{t+1} = A(t+1) + B$
 $= A + A + B$~~

~~$y_{t+2} = A(t+2) + B$
 $= A + 2A + B$~~

~~$(A + 2A + B) - 3(A + A + B) + 2(A + B) = 4t$~~

~~$A + -3A + 2A + (---)$~~

~~$0 \cdot t + (---) = 4t$~~

~~$A t^2 + (4A + B)t + (4A + 2B)$~~

~~$-3(A t^2 + (2A + B)t + (A + B))$~~

~~$+ 2(A t^2 + Bt)$~~ $= 4t$

$(4A + B - 6A - 3B + 2A)t = 4t$

$+ (4A + 2B - 3A - 3B) = 0$

$\left. \begin{array}{l} -2A = 4 \quad A = -2 \\ A - B = 0 \quad B = A = -2 \end{array} \right\} y_t^p = \underline{\underline{-2t^2 - 2t}}$

$y_t = \underline{\underline{At^2 + Bt}}$

$y_{t+1} = A(t+1)^2 + B(t+1)$
 $= \underline{\underline{At^2 + (2A + B)t + (A + B)}}$

$y_{t+2} = A(t+2)^2 + B(t+2)$
 $= \underline{\underline{At^2 + (4A + B)t + (4A + 2B)}}$

Difference eqn. with y_{t+2}, y_{t+1}, y_t = Second order difference eqn.

Why?

$$\Delta(y_t) = y_{t+1} - y_t$$

$$\begin{aligned}\Delta^2(y_t) &= (y_{t+2} - y_{t+1}) - (y_{t+1} - y_t) \\ &= y_{t+2} - 2y_{t+1} + y_t\end{aligned}$$

② System of difference equations

Ex: $y_{t+1} = y_t - z_t$
 $z_{t+1} = -y_t + 3z_t$ or $\begin{pmatrix} y_{t+1} \\ z_{t+1} \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} y_t \\ z_t \end{pmatrix}$

Solution methods: Homogeneous case

$\underline{y}_{t+1} = A \underline{y}_t$ has general solution $\underline{y}_t = C_1 \underline{v}_1 \lambda_1^t + \dots + C_n \underline{v}_n \lambda_n^t$

when A is diagonalizable, with eigen values $\lambda_1, \dots, \lambda_n$ and eigenvectors $\underline{v}_1, \dots, \underline{v}_n$ that are linearly independent.

Ex: $A = \begin{pmatrix} 1 & -1 \\ -1 & 3 \end{pmatrix}$ Eigenvalues: $\lambda^2 - 4\lambda + 2 = 0$
 $\lambda = \frac{4 \pm \sqrt{16 - 8}}{2} = 2 \pm \frac{\sqrt{8}}{2} = \underline{2 \pm \sqrt{2}}$

$\underline{y}_{t+1} = A \underline{y}_t$: $\underline{y}_t = C_1 \underline{v}_1 \cdot (2 + \sqrt{2})^t + C_2 \underline{v}_2 \cdot (2 - \sqrt{2})^t$

Ex: $\underline{y}_{t+1} = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \underline{y}_t$ $A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$

$\lambda=1$: $\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$ $x-y=0$ $\lambda^2 - 4\lambda + 3 = 0$
 $x=y, y$ free $\lambda=1, \lambda=3$
 $y \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow \underline{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\lambda=3$: $\begin{pmatrix} -1 & -1 \\ -1 & -1 \end{pmatrix}$ $-x-y=0$
 $x=-y, y$ free
 $y \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} \Rightarrow \underline{v}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

General solution: $\underline{y}_t = c_1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot 1^t + c_2 \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} \cdot 3^t$
 $= c_1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} \cdot 3^t$
 $\underline{y}_t = \underline{\underline{\begin{pmatrix} c_1 - c_2 \cdot 3^t \\ c_1 + c_2 \cdot 3^t \end{pmatrix}}}$

Ex: $\underline{y}_{t+1} = \begin{pmatrix} 0.75 & 0.05 \\ 0.25 & 0.95 \end{pmatrix} \underline{y}_t$ $A = \begin{pmatrix} 0.75 & 0.05 \\ 0.25 & 0.95 \end{pmatrix}$

regular Markov chain matrix

Eigenvalues: $\lambda^2 - 1.7\lambda + 0.7 = 0$
 $(\lambda-1)(\lambda-0.7) = 0$
 $\lambda=1, \lambda=0.7$

$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ 5x \end{pmatrix} = x \cdot \begin{pmatrix} 1 \\ 5 \end{pmatrix}$

$\lambda=1$: $\begin{pmatrix} -0.25 & 0.05 \\ -0.25 & -0.05 \end{pmatrix} \rightarrow \begin{pmatrix} -5 & 1 \\ 0 & 0 \end{pmatrix}$ $-5x+y=0$ $y=5x$ $\underline{v}_1 = \begin{pmatrix} 1 \\ 5 \end{pmatrix}$
 x free

$\lambda=0.7$: $\begin{pmatrix} 0.05 & 0.05 \\ -0.25 & -0.25 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$ $x+y=0$ $\underline{v}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$
 y free

Solution: $\underline{y}_t = c_1 \begin{pmatrix} 1 \\ 5 \end{pmatrix} \cdot 1^t + c_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix} \cdot 0.7^t$

$$= \underline{c_1 \cdot \begin{pmatrix} 1 \\ 5 \end{pmatrix} + c_2 \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} \cdot 0.7^t}$$

Ex: $\underline{y}_{t+1} = A \underline{y}_t + \underline{b} = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \underline{y}_t + \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

$$\underline{y}_{t+1} - \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \underline{y}_t = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \quad \text{inhomogeneous}$$

$$\underline{y}_t = \underline{y}_t^h + \underline{y}_t^p = \underline{c_1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot 1^t + c_2 \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} \cdot 3^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix}}$$

y_t^h : $\underline{y}_t^h = c_1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot 1^t + c_2 \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} \cdot 3^t$

since $\lambda_1 = 1, \lambda_2 = 3$ $\underline{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $\underline{v}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ (see previous ex.)

y_t^p : $\underline{y}_{t+1} - A \underline{y}_t = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ Guess: const. solution

$$\underline{y}_t = \underline{w} = \begin{pmatrix} A \\ B \end{pmatrix}$$

$$\underline{w} - A \underline{w} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \quad | \cdot (-1)$$

$$- \underline{w} + A \underline{w} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$A \underline{w} - \underline{w} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$(A - I) \underline{w} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \underline{w} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} 1 & -1 & -1 \\ -1 & 1 & 1 \end{array} \right) \xrightarrow{I_2} \left(\begin{array}{cc|c} 1 & -1 & -1 \\ 0 & 0 & 0 \end{array} \right)$$

$A - B = 1$
 $B \text{ free}$ $\rightarrow$ For example:
 $B = 0 \Rightarrow A = 1$
 $\underline{w} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

Summary: Linear difference equationsCases:

(a) First order linear: $y_{t+1} + ay_t = b_t$

(b) Second order linear: $y_{t+2} + ay_{t+1} + by_t = c_t$

Method: $y_t = y_t^h + y_t^p$

- where y_t^h is found using the characteristic eqn.

(a) $r + a = 0 \quad r = -a \Rightarrow y_t^h = \underline{C \cdot (-a)^t}$

(b) $r^2 + ar + b = 0$

if $r_1 \neq r_2$: $y_t^h = \underline{C_1 \cdot r_1^t + C_2 \cdot r_2^t}$

if $r_1 = r_2$: $y_t^h = \underline{C_1 \cdot r_1^t + C_2 \cdot t \cdot r_1^t}$

- and where y_t^p is one particular solution, that can be found by guessing a solution y_t with parameters and substitute into the eqn. to find the parameter values (remember to compute y_{t+1} , y_{t+2})

(c) Linear systems: $\underline{y}_{t+1} = \underline{A} \underline{y}_t = \underline{b}$

Method: $\underline{y}_t = \underline{y}_t^h + \underline{y}_t^p$

- where $y_t^h = C_1 \underline{v}_1 \lambda_1^t + \dots + C_n \underline{v}_n \lambda_n^t$, with $\lambda_i, \underline{v}_i$ eigenvalues and eigenvectors of A - and y_t^p is a constant solution $\underline{y}_t = \underline{w}$, that is

$$\underline{w} - \underline{A} \underline{w} = \underline{b} \Leftrightarrow \underline{A} \underline{w} + \underline{b} = \underline{w} \Leftrightarrow \underline{A} \underline{w} - \underline{w} = -\underline{b} \Leftrightarrow (\underline{A} - \underline{I}) \underline{w} = -\underline{b}$$