

$$1. \ a) \ y'' - 2y' - 3y = 4e^t$$

second order  
linear diff. equ.

$$y = y_h + y_p = \underline{\underline{C_1 e^{3t} + C_2 e^{-t} - e^t}}$$

$$\underline{y_h}: \ y'' - 2y' - 3y = 0$$

$$r^2 - 2r - 3 = 0 \quad \text{char. equ.}$$

$$r = \frac{2 \pm \sqrt{4 - 4(-3)}}{2}$$

$$= \frac{2 \pm 4}{2} = 3, -1$$

$$\rightarrow y_h = \underline{C_1 \cdot e^{3t} + C_2 e^{-t}}$$

$$\underline{y_p}: \ y'' - 2y' - 3y = 4e^t$$

$$\rightarrow f = 4e^t$$

$$f' = 4e^t$$

$$f'' = 4e^t$$

$$\left\{ \begin{array}{l} y = A \cdot e^t \\ y' = A e^t \\ y'' = A e^t \end{array} \right.$$

$$A e^t - 2(A e^t) - 3(A e^t) = 4e^t$$

$$e^t \cdot (A - 2A - 3A) = 4e^t$$

$$-4A = 4$$

$$A = -1$$

$$\rightarrow y = \underline{\underline{-e^t}}$$

$$b) \quad \underbrace{2ty - 1}_{h'_t} + \underbrace{t^2 y'}_{h'_y \cdot y'} = 0$$

$$h'_t + h'_y \cdot y' = 0$$

exact?

BI

$$\textcircled{1} \quad h'_t = 2ty - 1$$

$$\textcircled{2} \quad h'_y = t^2$$

$$\textcircled{1} \Rightarrow h = t^2 y - t + \alpha(y)$$

$$\textcircled{2}: \quad h'_y = (t^2 y - t + \alpha(y))'$$

$$= t^2 - 0 + \alpha'(y)$$

$$= t^2 + \alpha'(y)$$

$\Downarrow$

$$\textcircled{2} \quad t^2 + \alpha'(y) = t^2$$

$$\alpha'(y) = 0$$

can choose  $\alpha(y) = 0$

$\Downarrow$

$$h = t^2 y - t$$

Conclusion:

The diff. eqn. is exact and can be written

$$h'_t + h'_y \cdot y' = 0$$

with  $h = t^2 y - t$

$\Downarrow$

$$h = t^2 y - t = C$$

$$t^2 y = C + t$$

$$y = \frac{C + t}{t^2}$$

$$y = \frac{C}{t^2} + \frac{1}{t}$$

$$c) \quad 2ty \cdot y' = 1$$

Separable

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$$2y \cdot y' = \frac{1}{t}$$

$$\int 2y y' dt = \int \frac{1}{t} dt$$

$$\int 2y dy = \int \frac{1}{t} dt$$

$$y^2 = \ln|t| + C$$

$$y = \pm \sqrt{\ln|t| + C}$$

$$2. \quad a) \quad y' = 4e^y - 2$$

autonomous  $F(y) = 4e^y - 2$

$$\text{Eq. states: } F(y) = 4e^y - 2 = 0$$

$$4e^y = 2$$

$$e^y = 2/4 = 1/2$$

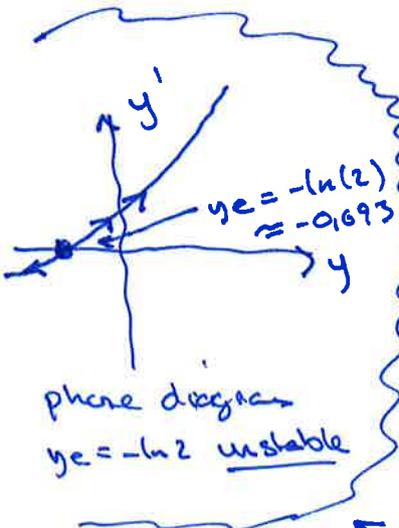
$$y_e = \ln(1/2) = \underline{\underline{-\ln(2)}}$$

Stability:

$$F'(y) = 4e^y$$

$$\stackrel{||}{=} F'(y_e) = 4 \cdot e^{\ln(1/2)} = 4 \cdot \frac{1}{2} = 2 > 0$$

By the Stability Th,  $y_e = -\ln(2)$  is unstable



Since there are no stable eq. states, there cannot be globally asympt. stable eq. states either.

Alternative argument for the fact that

$y_e = -\ln(2)$  is unstable: phase diagram.

$$b) \quad y' = y^2 - 3y + 2$$

autonomous

$$F(y) = y^2 - 3y + 2$$

BI

Eq. states:  $F(y) = y^2 - 3y + 2 = 0$

$$y = \frac{3 \pm \sqrt{9 - 4 \cdot 2}}{2} = \frac{3 \pm 1}{2} = 2, 1$$

$$\underline{y_e = 1}, \quad \underline{y_e = 2} \quad \text{eq. states.}$$

Stability:  $F'(y) = 2y - 3$

$$F'(1) = 2 \cdot 1 - 3 = -1 < 0$$

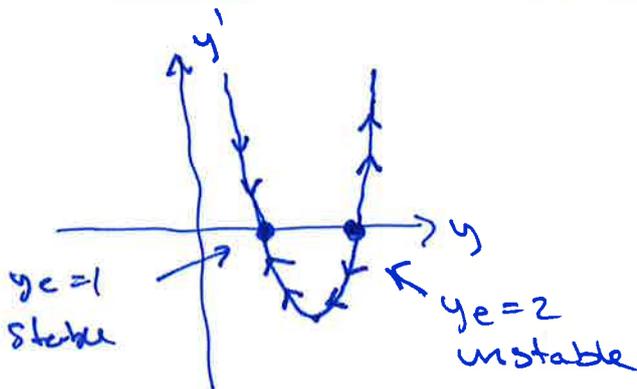
$$F'(2) = 2 \cdot 2 - 3 = 1 > 0$$

Stability then:

$$y_e = 1 \quad \underline{\text{stable}}$$

$$y_e = 2 \quad \underline{\text{unstable}}$$

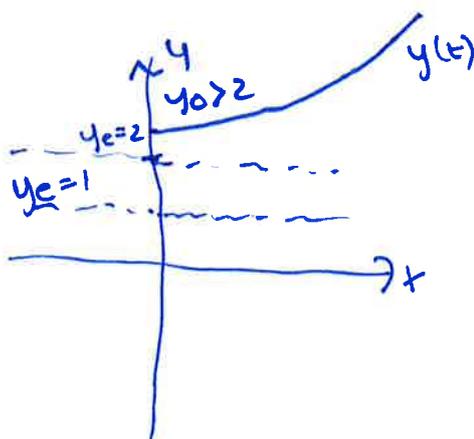
To check if  $y_e = 1$  is globally asymp. stable:



phase diagram

We see from the phase diagram that

$y_0 > 2 \Rightarrow y' > 0$ ,  $y$  increasing and the curve  $y(t)$  will not move towards  $y_e = 1$  as  $t$  increases.



Therefore,  $y_e = 1$  is stable but not globally asymp. stable.

$$\underline{3.} \quad \begin{pmatrix} y' \\ z' \end{pmatrix} = \begin{pmatrix} 4 & -2 \\ -5 & 1 \end{pmatrix} \begin{pmatrix} y \\ z \end{pmatrix}$$

a)

$A = \begin{pmatrix} 4 & -2 \\ -5 & 1 \end{pmatrix}$ : We need to find eigenvalues and eigenvectors for  $A$ , and check if  $A$  is diagonalizable.

Eigenvalues:  $\begin{vmatrix} 4-\lambda & -2 \\ -5 & 1-\lambda \end{vmatrix} = 0$

$$(4-\lambda)(1-\lambda) - 10 = 0$$

$$\lambda^2 - 5\lambda - 6 = 0$$

$$\lambda = \frac{5 \pm \sqrt{25 - 4 \cdot (-6)}}{2}$$

$$= \frac{5 \pm 7}{2} = 6, -1$$

two distinct  
eigenvalues

⇔



$\lambda_1 = 6$ ,  $\lambda_2 = -1$

$A$  is diagonalizable

Eigenvectors:

$$\lambda = 6: \begin{pmatrix} 4-6 & -2 & | & 0 \\ -5 & 1-6 & | & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & -2 & | & 0 \\ -5 & -5 & | & 0 \end{pmatrix}$$

$$-2x + 2y = 0 \Rightarrow x = -y$$

y free

$$E_6 = \text{span}(\underline{v}_1) \rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ y \end{pmatrix} = y \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} \Rightarrow \underline{v}_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\lambda = -1: \begin{pmatrix} 4+1 & -2 & | & 0 \\ -5 & 1+1 & | & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 5 & -2 & | & 0 \\ -5 & 2 & | & 0 \end{pmatrix}$$

$$5x - 2y = 0 \Rightarrow x = \frac{2}{5}y$$

y free

$$E_{-1} = \text{span}(\underline{v}_2) \quad \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{2}{5}y \\ y \end{pmatrix} = \frac{y}{5} \begin{pmatrix} 2 \\ 5 \end{pmatrix} \Rightarrow \underline{v}_2 = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

Note: could also have used  $\underline{v}_2 = \begin{pmatrix} 2/5 \\ 1 \end{pmatrix}$ , it gives the same span and the same solutions  $E_{-1}$ .

Cond:  $\lambda_1 = 6, \underline{v}_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$   
 $\lambda_2 = -1, \underline{v}_2 = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$

∥

General solution:

$$\begin{pmatrix} y \\ z \end{pmatrix} = C_1 \cdot \underline{v}_1 \cdot e^{2\lambda_1 t} + C_2 \cdot \underline{v}_2 \cdot e^{2\lambda_2 t}$$

$$= C_1 \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{6t} + C_2 \begin{pmatrix} 2 \\ 5 \end{pmatrix} e^{-t}$$

can be written:

$$y = -C_1 e^{6t} + 2C_2 e^{-t}$$

$$z = C_1 e^{6t} + 5C_2 e^{-t}$$

b) Eq. states:  $\begin{pmatrix} y' \\ z' \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 4 & -2 \\ -5 & 1 \end{pmatrix} \begin{pmatrix} y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

since  $|A| = 4 - 10 = -6 \neq 0$ , there is only the trivial solution  $\underline{y} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

∥

$\underline{y}_e = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  eq. state.

Stability:  $t \rightarrow \infty$  means that  $e^{6t} \rightarrow \infty$  (but  $e^{-t} \rightarrow 0$ )  
 therefore  $\underline{y}_e = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is unstable

For example:  $C_2 = 0, C_1 = a > 0$  small positive number gives  $y(t) \rightarrow -\infty, z(t) \rightarrow \infty$   
 This corresponds to  $\begin{pmatrix} y(0) \\ z(0) \end{pmatrix} = \begin{pmatrix} -a \\ a \end{pmatrix}$ , which is close to  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$  when  $a$  is small.